## { Refinement Types | Algebraic Effects }

Danel Ahman LFCS, University of Edinburgh

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- Refinement types & effects
- What do we feel is missing from refinement type systems?
  - A uniform treatment of various computational effects
  - General logical specifications for arbitrary effects
- Our way of bridging this gap
  - Algebraic effects and their logics
  - General effectful ref. types through algebraic effectful reasoning
  - Hopefully leads us to a general theory of effectful refinement types
- Some examples
  - State and pre-/post-conditions
  - Communication and sessions
  - Combination of the two



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- Most current refinement type systems target specific effects:
  - F7 extended with a refined state monad Borgström et. al. '09
    - $\blacksquare$  by adding a new computation type  $\{(s_0)\varphi_0\}x:\sigma\{(s_1)\varphi_1\}$
  - Monadic F\* with a Dijkstra monad Swamy et. al. '13 by adding a comp. type  $M \sigma wp$
  - Session types with linear refinement types Baltazar et. al. '12 by adding ref. ty.  $\{x:T\mid\varphi\}$  to session types (with  $\varphi$  in MLL)
- Some systems are more abstract in effects they consider:
  - - term refinements  $\varphi$ : bool, its(t),  $\varphi_1 \to \varphi_2$ ,  $(\varphi_1, \psi_1) \rightharpoonup (\varphi_2, \psi_2)$
    - lacktriangle world refinements  $\psi$ : formulas in linear logic
    - parametrized by a set of operations (together with a signature of operation refinements and a transition function for operations)



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  - Effective theory of type refinements | Mandelbaum et. al. '03
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• Consider a (fragment of a) simple communication language:

$$\frac{\Gamma \vdash t : A}{\Gamma \vdash \mathsf{return}\, t : FA} \qquad \frac{\Gamma \vdash t : FA \quad \Gamma, x : A \vdash u : FB}{\Gamma \vdash t \mathsf{to}\, x.\, u : FB}$$
 
$$\frac{\Gamma, x : \mathsf{nat} \vdash t : FA}{\Gamma \vdash \mathsf{receive}(x.t) : FA} \qquad \frac{\Gamma \vdash t : \mathsf{nat} \quad \Gamma \vdash u : FA}{\Gamma \vdash \mathsf{send}_t(u) : FA}$$

- Session refinements (inspired by session types)
  - $\blacksquare \ S(A) ::= end(A) \mid ?(x : \mathsf{nat}).S(A) \mid !(x : \mathsf{nat} \mid \varphi).S(A)$
- Example programs with their refinements:

  - $\blacksquare$   $\Gamma \vdash \mathsf{send}_t(\mathsf{send}_{t+1}(u)) : !(x : \mathsf{nat} \mid \top) . !(y : \mathsf{nat} \mid y > x) . S(1)$



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■ Pre- & post-condition specifications:

$$\forall \vec{x}.\{(x_0).\varphi_P\}x.A\{(x_1).\varphi_Q\}$$

■ Example program with its refinement:

$$\Gamma \vdash \mathsf{lookup}(x.\mathsf{update}_{x+1}(\mathsf{return}\,\star)) : \{(x_0).odd(x_0)\}x : 1\{(x_1).even(x_1)\}$$



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$$\begin{split} &\Gamma, x: \mathsf{nat} \vdash t: \forall \vec{x}, x_0.\{(x_1).\varphi_Q\}y: A\{(x_2).\varphi_R\} \\ &\Gamma \vdash \forall \vec{x}.\{(x_0).\top\}x: \mathsf{nat}\{(x_1).x_1 = x_0 \land x_1 = y\} \sqsubseteq \forall \vec{x}.\{(x_0).\varphi_P\}x: \mathsf{nat}\{(x_1).\varphi_Q\} \\ &\Gamma \vdash \mathsf{lookup}(x.t): \forall \vec{x}.\{(x_0).\varphi_P\}y: A\{(x_2).\varphi_R\} \\ &\Gamma \vdash t: \mathsf{nat} \quad \Gamma \vdash u: \forall \vec{x}, x_0.\{(x_1).\varphi_Q\}x: A\{(x_2).\varphi_R\} \\ &\underline{\Gamma \vdash \forall \vec{x}.\{(x_0).\top\}_-: 1\{(x_1).x_1 = t\} \sqsubseteq \forall \vec{x}.\{(x_0).\varphi_P\}_-: 1\{(x_1).\varphi_Q\}} \end{split}$$

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- Also want a combination of these languages and specifications
- For example, combining state and communication:

$$\forall \vec{x}. \{(x_0).\varphi_P\}(S(A) > x : A)\{(x_1).\varphi_Q\}$$

■ Example program with a composite refinement:

```
\{(x_0).\top\}(?(x:\mathsf{nat}).end(1) >\!\!\!> y:1) \\ \{(x_1).(x>x_0) \implies x_1=x_0-x\}
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- Non-standard combinations of specs.?



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### Our proposed approach



A computational language with algebraic effects

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- ref. types for general effectful specs.
- using algebraic effectful reasoning

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State language

Communication language

Language X



- The style of ref. types we work with (no effects for time being):
  - lacksquare  $\lambda$ -calculus with types  $A ::= \alpha \mid 1 \mid A_1 \times A_2 \mid A_1 \rightarrow A_2$
  - Refinement types  $\sigma ::= \alpha \mid 1 \mid \Sigma_{x:\sigma_1}\sigma_2 \mid \Pi_{x:\sigma_1}\sigma_2 \mid \{x:\sigma \mid \varphi\}$
  - Well-formed refinement types  $\Gamma \vdash \sigma : \text{Ref}(A)$ , e.g.:

$$\frac{\vdash \Gamma \text{ wf}}{\Gamma \vdash \alpha : \mathsf{Ref}(\alpha)} \frac{\Gamma \vdash \sigma_1 : \mathsf{Ref}(A_1) \qquad \Gamma, x : \sigma_1 \vdash \sigma_2 : \mathsf{Ref}(A_2)}{\Gamma \vdash \Pi_{x : \sigma_1} \sigma_2 : \mathsf{Ref}(A_1 \to A_2)} \frac{\Gamma \vdash \sigma : \mathsf{Ref}(A) \qquad \Gamma, x : A \vdash \varphi : \mathsf{prop}}{\Gamma \vdash \{x : \sigma \mid \varphi\} : \mathsf{Ref}(A)}$$

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- Let's look at effects algebraically (for example: state)
- Types (sets) of values (countable) and locations (fin.): Val, Loc
- Operation symbols:
  - $\blacksquare$  lookup : Loc  $\rightarrow$  Val
  - $\blacksquare$  update : Loc, Val  $\rightarrow 1$
- Enforce equations on derived terms:
  - $\qquad \mathsf{update}_{l,v}(\mathsf{lookup}_l(x.t)) = \mathsf{update}_{l,v}(t[v/x])$
  - $\qquad \mathsf{update}_{l,v}(\mathsf{update}_{l,v'}(t)) = \mathsf{update}_{l,v'}(t)$
  - $t = lookup_l(x.update_{l,x}(t))$
  - $\qquad \text{update}_{l,v}(\text{update}_{l',v'}(t)) = \text{update}_{l',v'}(\text{update}_{l,v}(t)) \qquad (l \neq l')$
  - ... Plotkin & Power '02
- Your usual monad through free algebra construction:
  - $T = UF = (Val^{Loc} \times -)^{Val^{Loc}}$



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## The programming language



 We use a variant of the Effect Calculus (closely related to Call-by-Push-Value) Egger et. al. '09, '12

Levy '01,'04

- Value and computation types:
  - $A ::= \alpha \mid 1 \mid A_1 \times A_2 \mid A_1 \to A_2 \mid FA$
  - $A ::= A_1 \times A_2 \mid A_1 \to A_2 \mid FA$
- $\blacksquare$  Terms t:

$$t ::= x \mid \star \mid \langle t_1, t_2 \rangle \mid \mathsf{proj}_i \, t \mid \lambda x.t \mid t_1(t_2) \mid \mathsf{return} \, t \mid t_1 \, \mathsf{to} \, x. \, t_2 \mid \mathsf{op}_{t_1}(x.t_2) \mid \mathsf{proj}_{t_1}(x.t_2) \mid \mathsf{proj}_{t_2}(x.t_2) \mid \mathsf{proj}_{t_1}(x.t_2) \mid \mathsf{proj}_{t_2}(x.t_2) \mid \mathsf{proj}_{$$

■ Well-typed terms  $\Gamma \vdash t : A$ , e.g.:

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## The programming language



 We use a variant of the Effect Calculus (closely related to Call-by-Push-Value) Egger et. al. '09, '12 Levy '01,'04

- Value and computation types:
  - $\blacksquare A ::= \alpha \mid 1 \mid A_1 \times A_2 \mid A_1 \rightarrow A_2 \mid FA$
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- This algebraic treatment of effects induces an effectful multi-sorted logic on EC:
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  - Formulas:  $\varphi ::= t_1 = t_2 \mid R(\vec{t}) \mid \pi(\vec{t}) \mid \neg \varphi \mid \varphi_1 \lor \varphi_2 \mid \exists x. \varphi$
  - Predicates:  $\pi ::= X \mid (\vec{x}).\varphi \mid \mu X.\pi \mid \nu X.\pi$
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- Based on the logic of algebraic effects for CBPV



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- The story is similar to the  $\lambda$ -calc. ref. types  $\Gamma \vdash \sigma : Ref(A)$
- We start with EC and its value & computation types:
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  - $\varphi'$ s do not induce subalgebras in general
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■ Well-typed terms follow the adj. model considerations:

$$\begin{array}{c|c} \Gamma \vdash t : \sigma & |\Gamma| \mid \Gamma^{\circ} \vdash \varphi[|t|/x] \\ \hline \Gamma \vdash t : \{x : \sigma \mid \varphi\} & \Gamma \vdash t : \{x : \sigma \mid \varphi\} \\ \hline \Gamma \vdash t : \sigma & \Gamma \vdash t : \sigma \\ \hline \Gamma \vdash \text{return } t : F\sigma & \Gamma \vdash t_1 \text{ to } x . t_2 : \underline{\tau} \\ \hline \Gamma \vdash \text{op}_{t_1}(x.t_2) : \underline{\tau} \end{array}$$

■ Also, more modular verification rules are derivable, e.g.:

$$\Gamma \vdash t_1 : \sigma_1 \quad |\sigma_1| = \beta \qquad \Gamma, x : \alpha \vdash t_2 : \sigma_2 \qquad |\sigma| = |\sigma_2| = \underline{A}$$

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Also, more modular verification rules are derivable, e.g.:

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$$\Gamma \vdash \mathsf{op}_{t_1}(x.t_2) : \sigma$$



- Recall the small state language:
  - induced by the 1-location state theory
- Recall the a grammar of session refinements:

$$S(A) ::= end(A) \mid !(x : \mathsf{nat} \mid \varphi).S(A) \mid \\ ?(y : \mathsf{nat}).S(A) \mid S_1(B); S_2(A)$$

■ They are defined as operations on predicates, e.g.:

```
 = end(A) \stackrel{\text{def}}{=} (x : FA). \exists x'. x = \operatorname{return} x'
```

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$$\blacksquare S(A); S(B) \stackrel{\mathsf{def}}{=} \dots$$



- Recall the small state language:
  - induced by the 1-location state theory
- Recall the a grammar of session refinements:
  - $S(A) ::= end(A) \mid !(x : \mathsf{nat} \mid \varphi).S(A) \mid \\ ?(y : \mathsf{nat}).S(A) \mid S_1(B); S_2(A)$
- They are defined as operations on predicates, e.g.:
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- Recall the small state language:
  - induced by the 1-location state theory
  - lacksquare receive :1 o nat  $\:$  ,  $\:$  send : nat  $\:$   $\to 1$
- Recall the a grammar of session refinements:

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#### **Examples: state**



- Recall the small state language:
  - induced by the 1-location state theory
  - lacksquare lookup : 1 o nat , update : nat o 1
- Formulas  $\varphi_P$  and  $\varphi_Q$  on states (on natural numbers)
- The pre- & post-condition spec.:

$$\forall \vec{x}.\{(x_0).\varphi_P\}y: A\{(x_1).\varphi_Q\} \stackrel{\text{def}}{=}$$

$$(x:FA).(\forall \vec{x'}.\forall x_s. \pi_P[\vec{x'}/\vec{x}, x_s/x_0] \implies \pi_{aux}(\vec{x'}, x_s, x_s, x))$$

where (for total correctness)

$$\begin{split} \pi_{aux} &\stackrel{\text{def}}{=} \mu X. ((\vec{x}, x_0, x_1, x). \\ & \left( \exists y. x = \mathsf{return} \, y \land \varphi_Q \right) \\ & \lor \left( \exists x'. x = \mathsf{lookup}(x. x'(x)) \land X \big( \vec{x}, x_0, x_1, x'(x_1) \big) \right) \\ & \lor \left( \exists x', x''. x = \mathsf{update}_{x'}(x'') \land X \big( \vec{x}, x_0, x', x'' \big) \right)) \end{split}$$

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#### **Examples: state**



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$$\forall \vec{x}. \{(x_0).\varphi_P\}(S(A) > x:A)\{(x_1).\varphi_Q\}$$

- How well can we represent it in our ref. ty. system?
- Combining underlying state & comm. calculi is easy:
  - induced by the tensor of effect theories
  - lacksquare semantics induced similarly (i.e.,  $T_{\otimes} = (T_{IO}(\mathsf{Val}^\mathsf{Loc} \times -))^{\mathsf{Val}^\mathsf{Loc}})$
- Combining refinement specs.:
  - not so straightforward, no obvious good combinators
  - similarity between ref. specs. and monads

$$\blacksquare \ldots \vee \Big(\exists x'.x = \mathsf{receive}(x.x'(x)) \wedge \\ \exists Y. \Big(S(x) \Longleftrightarrow (?(y : \mathsf{nat}).Y)\Big) \wedge X(\vec{x}, x_0, x_1, x, Y) \Big)$$



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#### To sum it up



A computational language with algebraic effects

+

- ref. types for general effectful specs.
- using algebraic effectful reasoning

State language

Communication language

Language X

- For the future:
  - allow ref. types in logic?
  - combinations of specs. more painlessly
  - other algebraic machinery (locality, handlers)
  - extension of simple ty. sys. with dependent refs. fibrationally